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Subject: Re: Different ways to model tractive effort  
Posted by [Joerg von Lingen](#) on Mon, 14 Sep 2020 07:13:02 GMT  
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Dear all,

it has been implemented for railML2.5 and described in wiki  
[http://wiki2.railml.org/wiki/RS:segmentTable\\_tractiveEffort](http://wiki2.railml.org/wiki/RS:segmentTable_tractiveEffort)

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Regards,  
Jörg von Lingen - Rollingstock Coordinator

Thomas Nygreen wrote on 05.03.2019 14:20:

- > Dear all,
  - >
  - > The current railML2 valueTable could support any of the
  - > segmented functions listed by Laura and Jörg, if we for
  - > each row apply the formula
  - >  $F = \text{Sum} ( y_z * v^z )$  for all  $z$
  - > where each value for  $z$  is given by columnHeader@zValue.
  - >
  - > If no column header is found and only one column is given,
  - > we would assume  $z = 0$ , meaning that  $F = y$ . This allows
  - > programs to keep listing the tractive effort for small speed
  - > steps.
  - >
  - > This approach would support any polynomial function, such as
  - > constant (only  $z=0$ ), linear (0 and 1), quadratic (0, 1, 2)
  - > and cubic (0, 1, 2, 3), the simple hyperbolic (-1, 0) and
  - > quadratic hyperbolic (-2) listed by Laura and Jörg, and
  - > other simple rational functions where there is no shift of
  - > the  $x$  variable.
  - >
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