Subject: Re: Harmonization with infrastructure aspects Posted by Joerg von Lingen on Thu, 02 Feb 2012 18:18:16 GMT View Forum Message <> Reply to Message

Dear all,

it needed a long business trip to find time to look into the details of the proposals. See answers below.

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On 05.01.2012 13:25, Susanne Wunsch wrote:
> Dear Jörg and all interested in this thread,
> wish you all a Happy new year and all the best for your business and
> family. :-)
>
> Carsten provided a very comprehensive suggestion for more detailed
> definition of speed changes in the "Infrastructure" subschema. There are
> some topics that are also met in the "Rollingstock" subschema. That's
> the reason I ask here for any comments.
>
> Susanne Wunsch <coord@common.railml.org> writes:
>> "Carsten Weber" < weber@irfp.de> writes:
       <xs:element name="axleLoad" minOccurs="0" maxOccurs="1">
       <xs:annotation>
>>>
        <xs:documentation>If any vehicle at the trains has a load at an axle
>>> higher than this value this speed limit has to be used.</xs:documentation>
       </xs:annotation>
>>>
      </xs:element>
>>>
>>
>> Good idea. I would propose it as an attribute and bind it to the railML
>> type "tWeightTons".
>>
>> What is Jörg von Lingens opinion (as Rollingstock coordinator) about the
>> terminus? Rollingstock already uses "axleLoad" and "axleWeight" for some
>> related information.
> Should we name the axle weight/load restriction for a speed profile
> "axleWeight" or "axleLoad"?
```

>>> <xs:element name="tiltingAngle" minOccurs="0" maxOccurs="1">
>>> <xs:annotation>
>>> <xs:documentation>Tilting parameters for which this speed profile is
>>> calculated.</xs:documentation>
>>> </xs:annotation>
>>> </xs:element>

The term "axleLoad" is used only in RS. This is used together with loadLimitMatrix containing permissible speeds in relation to axle loads.

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>> Good idea. I would spend a child element <tilting> for this and the
>> following kind of information. The attribute "angle" could be bound to
>> the railML type "tAngleDegQuadrant" for allowing 0° to 90°.
>>
>> Does a speedProfile covers only one tilting angle value or a range of
>> values or some single values?
>>
       <xs:element name="tiltingSpeed" minOccurs="0" maxOccurs="1">
>>>
       <xs:annotation>
>>>
        <xs:documentation>Tilting parameters for which this speed profile is
>>>
>>> calculated.</xs:documentation>
       </xs:annotation>
>>>
       </xs:element>
>>>
>> The terminus "speed" may be a bit misleading. I suppose, that is not
>> related to the "train speed" but to the "rate/speed of tilting", that
>> means the value of tilting degrees per second. I would call this
>> attribute "rate". Are there any other ideas?
   This attribute may be bound to the railML type "tSpeedDegreesPerSecond".
>>
>> There is another kind of information related to the tilting that comes
>> to my mind: the method of tilting. It could go into an attribute
   "method" that is bound to an enumeration of "active", "passive",
   "rollCompensation", "unknown", "other:anything".
>>
>> There is already a type "tTilting" in the rollingstock subschema. We
>> should coordinate these tilting issues with Jörg von Lingen (as
>> rollingstock coordinator).
> Maybe we could reuse the "tTilting" type from rollingstock providing the
> attributes "maxTiltingAngle", "actuation" and "tiltingSpeed" for the
> speed profiles.
It seems to me things are mixed up. If considering "tilting" within a speed
profile then it probably refers to the permissible speed with tilting function.
However, the "tiltingSpeed" in RS, which gives the of how quick the tilting is
de-/activated, is never related to the line speed. For rolling stock it is just
a physical characteristic of the tilting mechanism.
       <xs:element name="monitoringSystems" type="rail:eMonitoringSystems"</p>
>>>
>>> minOccurs="0">
>>>
       <xs:annotation>
        <xs:documentation>One of the listed monitoring systems has to be used
>>>
>>> by the trainPartSequence to use this speed profile.</xs:documentation>
       </xs:annotation>
>>>
       </xs:element>
>>>
>>> </xs:sequence>
```

>>

```
>>> </xs:complexType>
>>> <xs:complexType name="eMonitoringSystems">
      <xs:sequence>
>>>
      <xs:element name="MonitoringSystem" type="rail:tNationalSytemsType"</pre>
>>> minOccurs="1" maxOccurs="unbounded">
       <xs:annotation>
>>>
        <xs:documentation>type = tNationalSystemsType; Maybe it should be
>>>
>>> changed to a reference to a new base element monitoring system which would
>>> be referenced by vehicles, trainPartSequences, speedProfiles and
>>> trackElements. But also the defined types can be used as a
>>> key.</xs:documentation>
       </xs:annotation>
>>>
       </xs:element>
>>>
>>> </xs:sequence>
>>> </xs:complexType>
>>
>> That is an interesting idea. It touches Trac Ticket #111 [1].
>>
>> railML currently requires heavy repetition of obviously equal data
>> applying the <trainProtectionElement> in <ocsElements>. Thomas Albrecht
>> already pointed it out in 2009. [2] But a change of this structure
>> requires a non-downward-compatible change, that we may do with next
>> major release according to our release policy. See also Trac ticket #23
>> [3].
>>
    If it would be a blocking issue, we may mark the current element as
>>
     "deprecated" and allow for a "definition list"/"library"/"catalog" of
>>
    train protection elements inside the <infrastructure> element.
>>
      <trainProtectionSystem id="tpsLZB" name="LZB"
>>
       description="Linienförmige Zugbeeinflussung" xml:lang="de"
>>
       type="LZB" medium="inductive" monitoring="continuous"/>
>>
>>
    Along the <track> we could define the <trainProtectionElement>
     refering to one of the "definition list elements".
>>
>>
    The same way we could refer to various train protection systems from
>>
    within a <speedProfile>.
>>
>>
    Does this approach also work for different ETCS levels?
>>
>>
    This issues should be harmonized with the rollingstock implementation
>>
     (tNationalSystemsType). Contact: Jörg von Lingen.
>>
>
> There is a parallel unequal implementation of command-control-system
  elements in railML.
   * The Infrastructure subschema defines <trainProtectionElement>s,
```

> <balise>s, <trainDetector>s and <trackCircuitBorder>s.

>

- > * The Rollingstock subschema defines <etcs> with
- > <specificTransmissionModule> and <nationalSystem> with the same
- > intentions partly using the same basic railML types.

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Before changing everything it shall be clear what is really intended. The monitoring in RS describes the physical features of the trainborne equipment. The trainProtectionSystem in IS lists the systems which can be used for this line. This may include particular features. Any train protection within a speed profile is just a reference "permissible speed"="protection system". There is no need for further details in here.

- > I'm sure, we should harmonize this aspect regardless of the annoying
- > repetition effect in the Infrastructure subschema!

>

- >> [1] http://trac.assembla.com/railML/ticket/111
- >> [2]
- >> http://www.railml.org/web/index.php/previous-events.html?fil
- e=tl_files/railML.org/documents/events/slides/2009-10-06_tud resden_albrecht-interlocking.pdf
- >> [3] http://trac.assembla.com/railML/ticket/23

>

- > Thanks for any help and kind regards...
- > Susanne

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Best regards, Joerg v. Lingen

Rollingstock Coordinator